On 3-dimensional *f*-Kenmotsu Manifolds with semi-symmetric metric connection

Dr.N.V.C Shukla and Mantasha

(Department of Mathematics and Astronomy, University of Lucknow)

Abstract The main purpose of this paper is to exploration about f-Kenmotsu manifolds with semisymmetric metric connections. Some necessary and sufficient conditions for such manifolds to be η parallel are studied. Ricci tensor, Projective curvature tensor and Concircular curvature tensor have been studied on this manifold. Also we have constructed an example of a of f-kenmotsu manifolds to justify our results.

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1 Introduction

In 1958, M.M.Boothby and R.C.Wong [8] introduce the concept of odd dimensional manifold with contact and almost contact structure . K.Kenmotsu[6] in 1972 studied a class of almost contact metric manifolds and called them as a Kenmotsu Manifold. He also proved that if a Kenmotsu manifold satisfies the condition of R(X,Y). R = 0 then the manifold became of negative curvature -1 , where R is the Riemanian curvature tensor of type (1,3) . In 1924, Friedman and Schouten[1] introduced the notion of semi-symmetric metric connections on a differentiable manifold and the notion of semi-symmetric metric connection is a generelization of semi-symmetric metric connection is a generelization of semi-symmetric metric connection if its torsion tensor T is of the form,

where η is a 1-form.

$$T(X,Y) = \eta(Y)X - \eta(X)Y, \qquad (1.1)$$

In 1970, K.Yano[7] considered a semi-symmetric metric connection and studied some of its properties.

2 Preliminaries

Let M be a 3- dimensional differentiable manifold with an almost contact metric structure (ϕ, ξ, η, g), where ϕ is a (1,1)-tensor field , ξ is a vector field, η is a 1-form and g is a Riemannian metric on the manifold , satisfying the relations

$\phi^2 X = -X + n(X) \otimes \xi$	(2 1)
$\varphi X = X + \eta(X) \otimes \zeta,$	(2.1)
$\eta(\xi) = 1,$	(2.2)
$\eta(X) = g(X,\xi),$	(2.3)
$g(\phi X, \phi Y) = g(X, Y) - \eta(X)\eta(Y),$	(2.4)
$g(X,\phi Y) = -g(\phi X,Y),$	(2.5)
$\phi \xi = 0$,	(2.6)
$\eta\circ\phi=0$,	(2.7)

for any vector fields X, Y on the manifold M. The manifold M is called an f-Kenmotsu manifold if the covariant differentiation of ϕ satisfies the relation [5]

$$(\nabla_X \phi)Y = f(g(\phi X, Y)\xi - \eta(Y)\phi X), \tag{2.8}$$

where ∇ is the Levi-Civita connection of the f-Kenmotsu manifolds and f is a c^{∞} -function on the manifold. If $f=\beta$ =constant $\neq 0$, then the manifold is β -Kenmotsu manifold [13] and if f=0, then the manifold reduces to cosympletic manifold [13]. Moreover f-Kenmotsu manifold is called regular if $f^2 + f' \neq 0$, where $f' = \xi f$. From equation (2.2), we get

6 STA IL. 1 25. 3

$$\nabla_X \xi = f[X - \eta(X)\xi]. \tag{2.9}$$

In a 3- dimensional f-Kenmotsu manifold, we have [2]

$$R(X,Y)Z = g(Y,Z)QX - g(X,Z)QY + S(Y,Z)X - S(X,Z)Y - \frac{r}{2}(g(Y,Z)X - g(X,Z)Y).$$
(2.10)

$$R(X,Y)\xi = -(f^2 + f')(\eta(Y)X - \eta(X)Y), \qquad (2.11)$$

$$R(\xi, Y)Z = -(f^2 + f')(g(Y, Z)\xi - \eta(X)Y),$$
(2.12)

$$S(X,\xi) = -2(f^2 + f')\eta(X),$$
(2.13)

$$S(\xi,\xi) = -2(f^2 + f'), \tag{2.14}$$

$$Q\xi = -2(f^2 + f')\xi \quad , \tag{2.15}$$

where R, S and Q denote the Riemanian curvature tensor, Ricci tensor and Ricci operator respectively. As a consequence of equation (2.9) we also have,

$$(\nabla_X \eta)(Y) = fg(\phi X, \phi Y),$$
 (2.16)
 $S(\phi X, \phi Y) = S(X, Y) + 2(f^2 + f')\eta(X)\eta(Y),$ (2.17)

(2.19)

Also we have,

for all vector fields X,Y. In a 3-dimensional
$$f$$
-Kenmotsu manifold we also have [10]

$$R(X,Y)Z = \left(\frac{r}{2} + 2f^{2} + 2f'\right)(X \wedge Y)Z - \left(\frac{r}{2} + 3f^{2} + 3f'\right)(\eta(X)(\xi \wedge Y)Z + \eta(Y)(X \wedge \xi)Z),$$
(2.18)

and

$$S(X,Y) = \left(\frac{r}{2} + f^2 + f'\right)g(X,Y) - \left(\frac{r}{2} + 3f^2 + 3f'\right)\eta(X)\eta(Y),$$

where r is the scalar curvature and $f' = \xi f$.

3 *f*-Kenmotsu manifolds with semi-symmetric metric connection

Let M be a 3-dimensional f- Kenmotsu manifold and ∇ denotes the Levi-Civita connection on it . A linear connection $\tilde{\nabla}$ on M is said to be a semi-symmetric if the torsion tensor \tilde{T} of type (1,2) defined by,

$$\widetilde{T}(X,Y) = \widetilde{\nabla}_X Y - \widetilde{\nabla}_Y X - [X,Y], \tag{3.1}$$

satisfies,

$$\tilde{T}(X,Y) = \eta(Y)X - \eta(X)Y, \qquad (3.2)$$

for all vector fields X and Y on M . If moreover , the semi-symmetric connection $\widetilde{
abla}$ holds the relation $\widetilde{\nabla}_g = 0$ is called semi-symmetric metric connection. A semi-symmetric connection $\widetilde{\nabla}$ is said to be non-metric if $\tilde{\nabla}_a \neq 0$. A relation between a semi-symmetric metric and Levi-Civita connections is given as,

$$\widetilde{\nabla}_X Y = \nabla_X Y + \eta(Y) X - g(X, Y)\xi, \qquad (3.3)$$

for all vector fields $X, Y \in \chi(M)$ ([22]). With the help of equations (2.1),(2.2), (2.3),(2.4),(2.5) we can easily observe that

$$(\widetilde{\nabla}_{x}\eta)(Y) = (\nabla_{x}\eta)Y - \eta(X)\eta(Y) + g(X,Y),$$
(3.4)

and

$$\widetilde{\nabla}_X \phi(Y) = -g(X, \phi Y)\xi - 2\eta(Y)\phi X, \qquad (3.5)$$

If R and \tilde{R} denotes the curvature tensors with respect to the Levi-Civita and semi-symmetric metric connections of the manifold *M* respectively, then

$$\widetilde{R}(X,Y)Z = \widetilde{\nabla}_X \widetilde{\nabla}_Y Z - \widetilde{\nabla}_Y \widetilde{\nabla}_X Z - \widetilde{\nabla}[X,Y],$$
(3.6)

for all $X, Y \in \chi(M)$. In consequence of equations (2.1), (2.2), (2.3), (2.4), we have

$\tilde{R}(X,Y)Z = R(X,Y)Z + 2fg(X,Z)Y - 2fg(Y,Z)X$	the second
$+f\eta(Z)(X\eta(Y) - Y\eta(X)) + f'(\eta(X)g(Y,Z))$	(3.7)
$-\eta(Y)g(X,Z)) + \eta(Z)(Y\eta(X) - X\eta(Y))$	and a
$-Xg(Y,Z) + Yg(X,Z) + (\eta(X)g(Y,Z) - \eta(Y)g(X,Z))\xi,$	1 3 3 3

for all $X, Y, Z \in \chi(M)$, we can write,

$$\begin{split} \tilde{R}(X,Y)Z &= R(X,Y)Z - (f+1)[\eta(X)\eta(Z)Y - \eta(Y)\eta(Z)X] \\ &- (f+1)[g(X,Z)\eta(Y) - g(Y,Z)\eta(X)]\xi \\ &+ (2f+1)[g(X,Z)Y - g(Y,Z)X], \end{split}$$

now contracting equation(3.8) with respect to the vector field X, we get

$$\tilde{S}(Y,Z) = S(Y,Z) + (f+1)\eta(Y)\eta(Z) - (3f+1)g(Y,Z),$$

nich is similar to

$$\tilde{Q}Y = QY + (f+1)\eta(Y)\xi - (3f+1)Y,$$

where $ilde{Q}$ and Q denotes the Ricci operators corresponding to the respective connections $\widetilde{\nabla}$ and ∇ and now we have to defined $\tilde{S}(Y,Z) = g(\tilde{Q}Y,Z)$ and S(Y,Z) = g(QY,Z). Let e_i , i = 1, 2, 3, ..., n be an orthonormal basis of the tangent space at every point of manifold M. Now considering $Y = Z = e_i$ in equation (3.10) and taking summation over i, $1 \le i \le n$, we have

$$\tilde{r} = r - 8f - 2,$$
 (3.11)

(3.8

(3.9

(3.10)

where

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$$\tilde{r} = \sum_{i=1}^{n} \tilde{S}(e_i, e_i), \qquad (3.12)$$

which represents the scalar curvatures with respect to the connections $\tilde{\nabla}$ and ∇ respectively. A f-Kenmotsu manifold is said to be η -Einstein Manifold if its Ricci tensor S takes the form

	$S(X,Y) = ag(X,Y) + b\eta(X)\eta(Y).$		(3.13)
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for arbitrary vector fields X and Y, where a and b are smooth functions on manifold (M,g)[5]. If b=0, then η -Einstein manifold becomes Einstein manifold.

Theorem 3.1 Let M be a 3- dimensional f-Kenmotsu manifold equipped with a semi-symmetric metric connection $\tilde{\nabla}$. Then the Ricci tensor \tilde{S} on M is η -einstein with respect to semi-symmetric metric connection \tilde{M} .

Proof. Let M be a 3- dimensional f-Kenmotsu manifold with a semi-symmetric metric connection $\widetilde{\nabla}$. We know that Ricci tensor for f-Kenmotsu manifold is given as

$$\tilde{S}(Y,Z) = S(Y,Z) + (f+1)\eta(Y)\eta(Z) - (3f+1)g(Y,Z),$$
(3.14)

if we consider S(X, Y) = 0, then we get Ricci tensor is of the form

$$\tilde{S}(Y,Z) = (f+1)\eta(Y)\eta(Z) - (3f+1)g(Y,Z).$$
(3.15)

This shows that Ricci tensor \tilde{S} is of the form of η -Einstien manifold.

4 η -parallel Ricci tensor with semi-symmetric metric connection

Many authors studied the properties of η -parallel Ricci tensor and proved several results on it [8]. In this section we have to discussed about the various geometrical properties of η -parallel Ricci tensor with respect to the semi-symmetric metric connection $\tilde{\nabla}$. A Ricci tensor \tilde{S} of an n-dimensional Kenmotsu manifold M endowed with a semi-symmetric metric connection $\tilde{\nabla}$ is said to be η -parallel if it satisfies the following relation

$$(\widetilde{\nabla}_X \widetilde{S})(\phi Y, \phi Z) = 0,$$

for arbitrary vector fields X, Y and Z.

Theorem 4.1 Let *M* be a 3- dimensional *f*-Kenmotsu manifold equipped with a semi-symmetric metric connection $\tilde{\nabla}$. Then the Ricci tensor *S* is η -parallel with respect to semi-symmetric metric connection $\tilde{\nabla}$ on the manifold *M*.

Proof. Let *M* be a 3- dimensional *f*-Kenmotsu manifold with a semi-symmetric metric connection $\tilde{\nabla}$. We have

$$(\nabla_X \phi) Y = f(g(\phi X, Y)\xi - \eta(Y)\phi X), \tag{4.2}$$

$$\tilde{S}(X,Y) = \left(\frac{r}{2} + f^2 + f'\right)g(X,Y) - \left(\frac{r}{2} + 3f^2 + 3f'\right)(\eta(X)\eta(Y)),\tag{4.3}$$

now putting $X=\phi X$ and $Y=\phi Y$ in (4.3), we have

$$\tilde{S}(\phi X, \phi Y) = (\frac{r}{2} + f^2 + f')g(\phi X, \phi Y) - (\frac{r}{2} + 3f^2 + 3f')(\eta(\phi X)\eta(\phi Y)),$$
(4.4)

as we know that $\eta \phi = 0$ and using the equation which is given below

$$g(\phi X, \phi Y) = g(X, Y) - \eta(X)\eta(Y), \tag{4.5}$$

then we have

$$\tilde{S}(\phi X, \phi Y) = (\frac{r}{2} + f^2 + f')[g(X, Y) - \eta(X)\eta(Y)],$$
(4.6)

since we know that

TIJER2304430 TIJER - INTERNATIONAL RESEARCH JOURNAL www.tijer.org 147

(4.1)

$$\eta(X) = g(X,\xi), \eta(Y) = g(Y,\xi)$$
 (4.7)

so we get

$$\tilde{S}(\phi X, \phi Y) = (\frac{r}{2} + f^2 + f')[g(X, Y) - g(X, \xi)g(Y, \xi)],$$
(4.8)

now differentiating equation (4.8) covariantly with respect to vector field Z, we get

$$\widetilde{\nabla}_Z \widetilde{S}(\phi X, \phi Y) = 0. \tag{4.9}$$

as $\nabla_X g(Y,Z) = 0$

Hence *S* is η -parallel with respect to semi-symmetric metric connection $\overline{\nabla}$ on the manifold *M*.

Theorem 4.2 If the Ricci tensor \tilde{S} of a 3-dimensional f-Kenmotsu manifold M equipped with a semisymmetric metric connection $\tilde{\nabla}$ is η -parallel, then the scalar curvature for the semi-symmetric metric connection $\tilde{\nabla}$ is -8f'.

Proof. Let M be a 3-dimensional f-Kenmotsu manifold with semi-symmetric metric connection $\widetilde{\nabla}$. Let $e_i, i = 1, 2, 3, ..., n$ be an orthonormal basis of the tangent space at any point of the manifold M. From equation(3.11) we have scalar curvature \widetilde{r} of the form ,

$$\tilde{r} = r - 8f - 2$$
, \sim

Now differentiate \tilde{r} with respect to vector field X .

where $f' = \xi f$.

5 Concircular curvature tensor with semi-symmetric metric connection

 $d\tilde{r}(X) = -8f'$

It is known that a geodesic circle (a curve whose first curvature is constant and second curvature is identically zero) is not tranformed into a geodesic circle by the conformal transformation

$$\bar{g}_{ij} = \psi^2 g_{ij},\tag{5.1}$$

(4.10)

(4.11)

where g_{ij} denotes the fundamental tensor.K.Yano [7] proved about the conformal transformation , which is well-defined in eaquation (5.1), satisfying the partial differential equation

$$\psi_{i;j} = \phi g_{ij} \tag{5.2}$$

It is clearly alter a geodesic circle into a geodesic circle.Such kind of transformation is concircular transformation and the geometry deals with such transformation is known as concircular geometry [14] . A tensor field of type (1,3) on Riemannian manifold, which remains invariant under the concircular transformation defined by,

$$C(X,Y)Z = R(X,Y)Z - \frac{r}{n(n-1)}[g(Y,Z)X - g(X,Z)Y],$$
(5.3)

where R is the curvature tensor and r denotes the scalar curvature , is known as concircular curvature tensor [11].

Let M be a 3- dimensional f-Kenmotsu manifold equipped with a semi-symmetric metric connection $\tilde{\nabla}$. A concircular curvature tensor \tilde{C} with semi-symmetric metric connection $\tilde{\nabla}$ on the manifold M is a tensor field of type (1,3) defined as,

$$\tilde{C}(X,Y)Z = \tilde{R}(X,Y)Z - \frac{\tilde{r}}{n(n-1)}[g(Y,Z)X - g(X,Z)Y],$$
(5.4)

for all vector fields $X, Y, Z \in \chi(M)$. Here \tilde{R} and \tilde{r} are the curvature tensor and scalar curvature of the manifold M with semi symmetric metric connection $\tilde{\nabla}$ respectively.

Let M be a 3-dimensional f-kenmotsu manifold equipped with a semi-symmetric metric connection $\tilde{\nabla}$. A Projective curvature tensor \tilde{P} with semi-symmetric metric connection $\tilde{\nabla}$ on the manifold M is a tensor field of type (1,3) is given as,

$$\tilde{P}(X,Y)Z = \tilde{R}(X,Y)Z - \frac{1}{n-1}[\tilde{S}(Y,Z)X - \tilde{S}(X,Z)Y]$$
(5.5)

for all vector fields $X, Y, Z \in \chi(M)$. Here \tilde{R} and \tilde{S} denotes the curvature tensor and Ricci tensor of the manifold M with semi-symmetric metric connection $\tilde{\nabla}$ respectively.

Theorem 5.1 A 3-dimensional f-Kenmotsu manifold is always ξ -projectively flat.

Proof. Let *M* ba a 3-dimensional *f*-Kenmotsu manifold .The Riemannian curvature tensor R(X,Y)Z and Ricci tensor S(X,Y) in 3-dimensional *f*-Kenmotsu manifold is defined as,

$$R(X,Y)Z = (\frac{r}{2} + 2f^2 + 2f')(X \wedge Y)Z - (\frac{r}{2} + 3f^2 + 3f')(\eta(X)(\xi \wedge Y)Z + \eta(Y)(X \wedge \xi)Z).$$

(5.6)

(5.7)

(5.8)

(5.9)

(5.10)

and

$$S(X,Y) = (\frac{r}{2} + f^2 + f')g(X,Y) - (\frac{r}{2} + 3f^2 + 3f')\eta(X)\eta(Y),$$

where r is the scalar curvature and $f' = \xi f$. From equation (5.6) putting $Z = \xi$, we have

$$R(X,Y)\xi = -(f^2 + f')[\eta(Y)X - \eta(X)Y].$$

In equation(5.7) putting $Y = \xi$, we have

$$S(X,\xi) = -2(f^2 + f')\eta(X).$$

using equations (5.8) and (5.9) ,in equation(5.5), we have

$$\tilde{P}(X,Y)\xi = 0.$$

which shows that a 3-dimensional f-Kenmotsu manifold is always ξ -projectively flat.

Theorem 5.2 If the Ricci tensor \tilde{S} of a 3- dimensional f-Kenmotsu manifold M endowed with a semisymmetric metric connection $\tilde{\nabla}$ is η -parallel. Then the following results on M are equivalent, i)Ricci tensor is cyclic parallel,

ii) $\tilde{S}(Y,Z) = -2(n-1)g(Y,Z),$ iii) $\tilde{r} = -2n(n-1)$

Proof (i): Let M be a f-Kenmotsu manifold with respect to semi-symmetric metric connection. We have

$\eta(\xi) =$	1,	(5.11)
$\phi^2 = -$	$I + \eta \otimes \xi$,	(5.12)
g(X,Y)	$= g(\phi X, \phi Y) + \eta(X)\eta(Y),$	(5.13)
S(φX, ¢	$bY) = S(X,Y) + (n-1)\eta(X)\eta(Y),$	(5.14)
$\tilde{S}(Y,Z)$	$= S(Y,Z) - (3n-5)g(Y,Z) + 2(n-2)\eta(Y)\eta(Z),$	(5.15)
TIJER2304430	TIJER - INTERNATIONAL RESEARCH JOURNAL www.tijer.org	149

from equations (5.11), (5.12), (5.13), (5.14) and (5.15), we get

$$\tilde{S}(\phi Y, \phi Z) = \tilde{S}(Y, Z) + 2(n-1)\eta(Y)\eta(Z),$$
now differentiating covarinatly equation (5.16) with respect to *X*, then we have
(5.16)

$$\widetilde{\nabla}_{X}\widetilde{S}(\phi Y, \phi Z) = \widetilde{\nabla}_{X}S(Y, Z) - \widetilde{S}(\widetilde{\nabla}_{X}(\phi Y), \phi Z) - \widetilde{S}(\phi Y, \widetilde{\nabla}_{X}(\phi Z)),$$
(5.17)

and since we clearly have

$$\widetilde{\nabla}_X \widetilde{S}(\phi Y, \phi Z) = \widetilde{\nabla}_X \widetilde{S}(Y, Z), \tag{5.18}$$

after some calculation ,we get

$$\widetilde{\nabla}_{X}\widetilde{S}(Y,Z) = -2\eta(Y)\widetilde{S}(X,Z) + \eta(Z)\widetilde{S}(X,Y) -4(n-1)\eta(Y)g(X,Z) + \eta(Z)g(X,Y),$$
(5.19)

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$$\widetilde{\nabla}_{Y}\widetilde{S}(Z,X) = -2\eta(Z)\widetilde{S}(Y,X) + \eta(X)\widetilde{S}(Y,Z) -4(n-1)\eta(Z)g(Y,X) + \eta(X)g(Y,Z),$$
(5.20)

$$\widetilde{\nabla}_{Z}\widetilde{S}(X,Y) = -2\eta(X)\widetilde{S}(Z,Y) + \eta(Y)\widetilde{S}(Z,X) -4(n-1)\eta(X)g(Z,Y) + \eta(Y)g(Z,X),$$

now adding equations (5.19), (5.20) and (5.21) then we have,

$$\widetilde{\nabla}_X \widetilde{S}(Y, Z) + \widetilde{\nabla}_Y \widetilde{S}(Z, X) + \widetilde{\nabla}_Z \widetilde{S}(X, Y) = 0.$$
(5.22)

(5.21)

(5.24)

(5.25)

(5.26)

i.e Ricci tensor \tilde{S} is cyclic parallel. *Proof (ii):* We know that

we have

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$$\eta(\xi) = 1, \varphi^{-} = -I + \eta \otimes \xi, \quad (5.23)$$

$$S(X,\xi) = -(n-1)\eta(X),$$

$$S(Y,Z) = S(Y,Z) - (3n-5)g(Y,Z) + 2(n-2)\eta(Y)\eta(Z),$$

$$\tilde{S}(Y,\xi) = -2(n-1)\eta(Y),$$

we know that

so we have,

$$\eta(X) = g(X,\xi)$$
(5.27)
$$\tilde{S}(Y,\xi) = -2(n-1)g(Y,\xi),$$
(5.28)

Proof (iii): Let e_i , i = 1, 2, 3, ..., n be an orthonormal basis of the tangent space at any point of the f-Kenmotsu manifold M. Putting $Y = Z = e_i$ in equation(5.28) and taking summation over i, 1<i<n, then we get

$$\tilde{r} = -2n(n-1).$$
 (5.29)

Theorem 5.3 In a 3-dimensional f-Kenmotsu manifold M with Levi-civita connection ∇ , we have

$$R(X,Y)Z + R(Y,Z)X + R(Z,X)Y = 0$$
(5.30)

Proof. Let *M* be a 3-dimensional *f*-Kenmotsu manifold with semi-symmetric metric connection ∇ . we know that Ricci curvature tensor

$$R(X,Y)Z = g(Y,Z)QX - g(X,Z)QY + S(Y,Z)X - S(X,Z)Y - \frac{r}{2}(g(Y,Z)X - g(X,Z)Y),$$
(5.31)

In similar way we have

$$R(Y,Z)X = g(Z,X)QY - g(Y,X)QZ + S(Z,X)Y - S(Y,X)Z - \frac{r}{2}(g(Z,X)Y - g(Y,X)Z),$$

(5.32)

g(Z,Y)QX

g(Z,Y)X,

$$R(Z,X)Y = g(X,Y)QZ - g(Z,Y)QX + S(X,Y)Z - S(Z,Y)X - \frac{r}{2}(g(X,Y)Z - g(Z,Y)X),$$
(5.33)

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On adding equation (5.31), (5.32), (5.33), we have

$$R(X,Y)Z + R(Y,Z)X + R(Z,X)Y = g(Y,Z)QX + g(Z,X)QY + g(X,Y)QZ - (X,Z)QY - (Y,X)QZ - (Y,X)QX - S(Y,Z)X - S(X,Z)Y + S(Z,X)Y - S(Y,X)Z + S(X,Y)Z - S(Z,Y)X - \frac{r}{2}g(Y,Z)X - g(X,Z)Y + g(Z,X)Y - g(Y,X)Z + g(X,Y)Z - (5.34)$$

since g is Riemannian metric which is symmetric and Ricci tensor S which is also symmetric i.e

$$g(Z,X) = g(X,Z), \qquad S(X,Y) = S(Y,X)$$

$$R(X,Y)Z + R(Y,Z)X + R(Z,X)Y = 0. \qquad (5.35)$$

6 Example

so we have,

We consider a 3-dimensional *f*-Kenmotsu manifold with semi-symmetric metric connections

$$\widetilde{M} = [x_1, x_2, t \in R^3: t \neq 0]$$
(6.1)

where (x_1, x_2, t) are the standadrd coordinates in R. Let us choose the vector fields

$$e_1 = t^2 \frac{\partial}{\partial x_1},\tag{6.2}$$

$$e_2 = t^2 \frac{\partial}{\partial x_2},\tag{6.3}$$

$$e_3 = \frac{\partial}{\partial_t},\tag{6.4}$$

which are linearly independent at each point of \tilde{M} . Now we define the metric g such that e_1, e_2, e_3 is an orthonormal basis of \tilde{M} i.e,

 $g(e_i, e_j) = 1 if i = j$ $= 0 if i \neq j, where 1 < i, j < 3. (6.5)$

Now consider a 1-form η which is defined by

$$\eta(X) = g(X, e_3), \qquad X \in \chi(\widetilde{M})$$

We choose $e_3 = \xi$. We define the tensor field ϕ by $\phi(e_1) = -e_2$, $\phi(e_2) = e_1$, $\phi(e_3) = 0$.

The linear property of g and ϕ showing that

$$\eta(e_3) = 1,$$
 $\phi^2(X) = -X + \eta(X)e_3,$ $g(\phi X, \phi Y) = g(X, Y) - \eta(X)\eta(Y),$
(6.6)

for any vector fields X, Y on \widetilde{M} . Then $\widetilde{M}(\phi, \xi, \eta, g)$ forms an almost contact manifold with $e_3 = \xi$. Let ∇ be the levi-civita connection with respect to the metric g, then we have

$$[e_3, e_i] = \frac{2}{t}e_i$$
, $i = 1, 2, 3$ and $[e_i, e_j] = 0$ (6.7)

otherwise . Now using Koszul's formula , we get

$$\begin{aligned} \nabla_{e_1} e_1 &= (2/t) e_3, & (6.8) \\ \nabla_{e_1} e_3 &= -(2/t) e_1, & (6.9) \\ \nabla_{e_2} e_3 &= -(2/t) e_2, & (6.10) \\ \nabla_{e_2} e_2 &= (2/t) e_3, & (6.11) \\ \nabla_{e_3} e_3 &= (2/t) e_1, & (6.12) \\ \nabla_{e_i} e_j &= 0, otherwise. & (6.13) \end{aligned}$$

$$\nabla_X \xi = f(X - \eta(X)\xi) \tag{6.14}$$

for $\xi = e_3$, and $f = -\frac{2}{t}$. Hence we can say that M is an f-Kenmotsu manifold. Again since $f^2 + f' \neq 0$, so that the manifold is called regular f-Kenmotsu manifold. Let M be a subset of \widetilde{M} and consider the immersion $h: M \to \widetilde{M}$ defined by $h(x_1, x_2, t) = (x_1, x_2, 0, 0, t)$. It is easy to prove that $M = (x_1, x_2, t) \in R^3: t \neq 0$ is a subamnifold \widetilde{M} where (x_1, x_2, t) are the standard coordinates of (e_1, e_2, e_3) . now we choose the vector fields such as

$$e_{1} = t^{2} \frac{\partial}{\partial x_{1}},$$

$$e_{2} = t^{2} \frac{\partial}{\partial x_{2}},$$

$$e_{3} = \frac{\partial}{\partial t}.$$
(6.15)
(6.16)
(6.17)

We define g_1 such that $[e_1, e_2, e_3]$ is an orthonormal basis of M. that is,

$$g_1(e_i, e_j) = 1$$
 if $i = j$ (6.18)

 $= 0 if i \neq j, (6.19)$

where i, j = 1, 2, 3.

The above re

We define a 1-form η_1 and a (1,1)tensor ϕ_1 as,

 $\eta_1 = g_1(X, e_3), \qquad \phi_1(e_1) = -e_2, \qquad \phi_1(e_2) = e_1, \qquad \phi_1(e_3) = 0, \quad (6.20)$

The linearity property of g_1 and ϕ_1 shows that

$$\eta_1(e_3) = 1, \qquad \phi^2 X = -X + \eta_1(X)e_3,$$
(6.21)

$$g_1(\phi_1 X, \phi_1 Y) = g_1(X, Y) - \eta_1(X)\eta_1(Y), \tag{6.22}$$

for any vector fields X, Y on $M(\phi_1, \xi, \eta_1, g_1)$. It is seen that M is manifold of \widetilde{M} with $e_3 = \xi$. Moreover, let ∇ be the Levi-civita connection with respect to the given metric g_1 [3][4]. Then we have following results

$$[e_3, e_i] = \frac{2}{t}e_i, i = 1,2$$
 and $[e_i, e_j] = 0,$ otherwise. (6.23)

Again using Koszul's formula, we obtain the following

$$\begin{aligned} \nabla_{e_1} e_1 &= (\frac{2}{t} - 1) e_3, \\ \nabla_{e_1} e_3 &= (\frac{-2}{t} + 1) e_1, \\ \nabla_{e_2} e_3 &= -\frac{2}{t} e_3 + e^2, \\ \nabla_{e_2} e_2 &= (\frac{2}{t} - 1) e_3, \\ \nabla_{e_i} e_j &= 0, otherwise. \end{aligned}$$
 (6.24) (6.24) (6.25) (6.25) (6.26) (6.26) (6.26) (6.26) (6.27) (6.28)

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